

# NAG Toolbox for MATLAB

## f04bg

### 1 Purpose

f04bg computes the solution to a real system of linear equations  $AX = B$ , where  $A$  is an  $n$  by  $n$  symmetric positive-definite tridiagonal matrix and  $X$  and  $B$  are  $n$  by  $r$  matrices. An estimate of the condition number of  $A$  and an error bound for the computed solution are also returned.

### 2 Syntax

```
[d, e, b, rcond, errbnd, ifail] = f04bg(d, e, b, 'n', n, 'nrhs_p',
nrhs_p)
```

### 3 Description

$A$  is factorized as  $A = LDL^T$ , where  $L$  is a unit lower bidiagonal matrix and  $D$  is diagonal, and the factored form of  $A$  is then used to solve the system of equations.

### 4 References

Anderson E, Bai Z, Bischof C, Blackford S, Demmel J, Dongarra J J, Du Croz J J, Greenbaum A, Hammarling S, McKenney A and Sorensen D 1999 *LAPACK Users' Guide* (3rd Edition) SIAM, Philadelphia URL: <http://www.netlib.org/lapack/lug>

Higham N J 2002 *Accuracy and Stability of Numerical Algorithms* (2nd Edition) SIAM, Philadelphia

### 5 Parameters

#### 5.1 Compulsory Input Parameters

- 1: **d(\*)** – double array

**Note:** the dimension of the array **d** must be at least  $\max(1, n)$ .

Must contain the  $n$  diagonal elements of the tridiagonal matrix  $A$ .

- 2: **e(\*)** – double array

**Note:** the dimension of the array **e** must be at least  $\max(1, n - 1)$ .

Must contain the  $(n - 1)$  subdiagonal elements of the tridiagonal matrix  $A$ .

- 3: **b(ldb,\*)** – double array

The first dimension of the array **b** must be at least  $\max(1, n)$

The second dimension of the array must be at least  $\max(1, \text{nrhs\_p})$ . To solve the equations  $Ax = b$ , where  $b$  is a single right-hand side, **b** may be supplied as a one-dimensional array with length **ldb** =  $\max(1, n)$

The  $n$  by  $r$  matrix of right-hand sides  $B$ .

#### 5.2 Optional Input Parameters

- 1: **n** – int32 scalar

*Default:* The dimension of the array **d**.

The number of linear equations  $n$ , i.e., the order of the matrix  $A$ .

*Constraint:*  $\mathbf{n} \geq 0$ .

2: **nrhs\_p** – int32 scalar

*Default:* The second dimension of the array **b**.

The number of right-hand sides  $r$ , i.e., the number of columns of the matrix  $B$ .

*Constraint:* **nrhs\_p**  $\geq 0$ .

### 5.3 Input Parameters Omitted from the MATLAB Interface

ldb

### 5.4 Output Parameters

1: **d(\*)** – double array

**Note:** the dimension of the array **d** must be at least  $\max(1, \mathbf{n})$ .

If **ifail** = 0 or  $Np1$ , **d** contains the  $n$  diagonal elements of the diagonal matrix  $D$  from the  $LDL^T$  factorization of  $A$ .

2: **e(\*)** – double array

**Note:** the dimension of the array **e** must be at least  $\max(1, \mathbf{n} - 1)$ .

If **ifail** = 0 or  $Np1$ , **e** contains the  $(n - 1)$  subdiagonal elements of the unit lower bidiagonal matrix  $L$  from the  $LDL^T$  factorization of  $A$ . (**e** can also be regarded as the superdiagonal of the unit upper bidiagonal factor  $U$  from the  $U^T D U$  factorization of  $A$ .)

3: **b(ldb,\*)** – double array

The first dimension of the array **b** must be at least  $\max(1, \mathbf{n})$

The second dimension of the array must be at least  $\max(1, \mathbf{nrhs\_p})$ . To solve the equations  $Ax = b$ , where  $b$  is a single right-hand side, **b** may be supplied as a one-dimensional array with length **ldb** =  $\max(1, \mathbf{n})$

If **ifail** = 0 or  $Np1$ , the  $n$  by  $r$  solution matrix  $X$ .

4: **rcond** – double scalar

If **ifail** = 0 or  $Np1$ , an estimate of the reciprocal of the condition number of the matrix  $A$ , computed as  $\mathbf{rcond} = 1 / \left( \|A\|_1 \|A^{-1}\|_1 \right)$ .

5: **errbnd** – double scalar

If **ifail** = 0 or  $Np1$ , an estimate of the forward error bound for a computed solution  $\hat{x}$ , such that  $\|\hat{x} - x\|_1 / \|x\|_1 \leq \mathbf{errbnd}$ , where  $\hat{x}$  is a column of the computed solution returned in the array **b** and  $x$  is the corresponding column of the exact solution  $X$ . If **rcond** is less than *machine precision*, then **errbnd** is returned as unity.

6: **ifail** – int32 scalar

0 unless the function detects an error (see Section 6).

## 6 Error Indicators and Warnings

Errors or warnings detected by the function:

**ifail** < 0 and **ifail** ≠ −999

If **ifail** = − $i$ , the  $i$ th argument had an illegal value.

**ifail** = −999

Allocation of memory failed. The double allocatable memory required is **n**. In this case the factorization and the solution  $X$  have been computed, but **rcond** and **errbnd** have not been computed.

**ifail** > 0 and **ifail** ≤  $N$

If **ifail** =  $i$ , the leading minor of order  $i$  of  $A$  is not positive-definite. The factorization could not be completed, and the solution has not been computed.

**ifail** =  $N + 1$

**rcond** is less than *machine precision*, so that the matrix  $A$  is numerically singular. A solution to the equations  $AX = B$  has nevertheless been computed.

## 7 Accuracy

The computed solution for a single right-hand side,  $\hat{x}$ , satisfies an equation of the form

$$(A + E)\hat{x} = b,$$

where

$$\|E\|_1 = O(\epsilon)\|A\|_1$$

and  $\epsilon$  is the *machine precision*. An approximate error bound for the computed solution is given by

$$\frac{\|\hat{x} - x\|_1}{\|x\|_1} \leq \kappa(A) \frac{\|E\|_1}{\|A\|_1},$$

where  $\kappa(A) = \|A^{-1}\|_1 \|A\|_1$ , the condition number of  $A$  with respect to the solution of the linear equations. f04bg uses the approximation  $\|E\|_1 = \epsilon \|A\|_1$  to estimate **errbnd**. See Section 4.4 of Anderson *et al.* 1999 for further details.

## 8 Further Comments

The total number of floating-point operations required to solve the equations  $AX = B$  is proportional to  $nr$ . The condition number estimation requires  $O(n)$  floating-point operations.

See Section 15.3 of Higham 2002 for further details on computing the condition number of tridiagonal matrices.

The complex analogue of f04bg is f04cg.

## 9 Example

```
d = [4;
      10;
      29;
      25;
      5];
e = [-2;
      -6;
      15];
```

```
      8];  
b = [6, 10;  
     9, 4;  
     2, 9;  
    14, 65;  
     7, 23];  
[dOut, eOut, bOut, rcond, errbnd, ifail] = f04bg(d, e, b)
```

```
dOut =  
     4  
     9  
    25  
    16  
     1  
eOut =  
    -0.5000  
    -0.6667  
     0.6000  
     0.5000  
bOut =  
     2.5000     2.0000  
     2.0000    -1.0000  
     1.0000    -3.0000  
    -1.0000     6.0000  
     3.0000    -5.0000  
rcond =  
     0.0095  
errbnd =  
    1.1669e-14  
ifail =  
         0
```